

# Calculating the full leaky Lamb wave dispersion characteristics

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# Motivation

Guided ultrasonic waves in solid media:

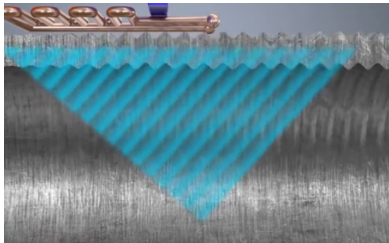


Figure: Wave inside the pipe wall<sup>1</sup>

- nondestructive testing
  - long range inspection
  - e. g. inspection of pipes
- ultrasonic sensing
  - e. g. flow metering

How does the *interaction* between the plate and the adjacent fluid take place?

<sup>1</sup>ROSEN Group. *ROSEN EMAT Flowmeter*. 2018. URL: <http://flowmeter.rosen-group.com/>

# Content

- 1 Motivation
- 2 Leaky Lamb waves
- 3 Change of variable
- 4 Results
- 5 Conclusion

# Leaky Lamb waves – Introduction

- **leaky Lamb waves:** guided waves inside a plate which is in contact with a fluid
- leakage of energy into the adjacent fluid
- many modes exist
- each with a unique displacement structure

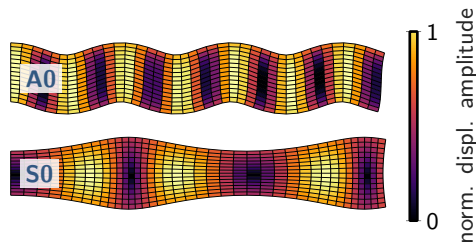


Figure: Basic modes in a **free** plate.

**A0:** anti-symmetric Mode. **S0:** symmetric Mode.

- They are dispersive:

## Dispersion

wavenumber  $k_x$  depends on frequency  $f$ :

$$k_x = k_x(f) \quad \Leftrightarrow \quad c_p = c_p(f)$$

- The dependence is implicitly given by the **characteristic equation**:

$$F(k_x, f) = 0.$$

- It is transcendental!
  - **numerical methods** are required
  - badly conditioned problem!

# Leaky Lamb waves – Modeling

- **plate:** assume harmonic wave propagation in  $x$ -direction:

$$\varphi_p(x, y, t) := \varphi(y) e^{i(k_x x - \omega t)}$$

$$\Psi_p(x, y, t) := i\Psi(y) e^{i(k_x x - \omega t)}$$

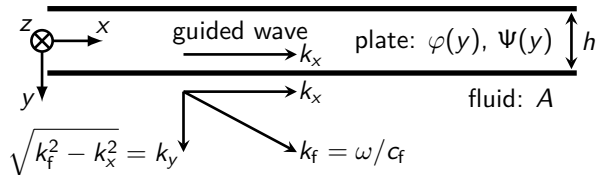
- **half-space**  $y > h/2$  (fluid domain)
  - open domain: exchange of energy
  - assume plane harmonic wave:

$$\varphi_f(x, y, t) := A e^{i k_y y} e^{i(k_x x - \omega t)}$$

→ scalar degree of freedom  $A$

**closed computational domain**

$$y \in [-h/2, h/2]$$



In terms of the potentials  $q = [\varphi(y), \Psi(y), A]^T$ , write:

- 1 equations of motion
  - 2 top boundary conditions
  - 3 bottom interface conditions
- results in a

**differential, nonlinear  
eigenvalue problem in  $k_x$**

**exact fluid-structure interaction**

# Leaky Lamb wave problem

- to solve on a computer
  - discretize the differential eigenvalue problem  
(e. g., spectral collocation, finite elements, finite differences)
  - **algebraic** nonlinear eigenvalue problem

## nonlinear eigenvalue problem: leaky Lamb waves

$$\underline{\underline{F}}(k_x)\underline{q} = \underline{0}, \quad \text{with} \quad \underline{\underline{F}}(k_x) = k_x^2 \underline{\underline{A}}_2 + k_x \underline{\underline{A}}_1 + \underline{\underline{A}}_0 + ik_y \underline{\underline{B}},$$

$$\text{where } k_y = \sqrt{k_f^2 - k_x^2}.$$

- the matrix function  $\underline{\underline{F}}(k_x)$  is:

nonlinear

not unique

not holomorphic

⇒ difficulties when solving

# Common approaches

- nonlinear eigenvalue solvers (e. g. iterative linearization, contour integration)
  - not always reliable <sup>4</sup>, e. g., might not find all solutions.
  - no standard methods
- perfectly matched layer (PML)
  - additional discretization of fluid
  - spurious eigenvalues need to be discarded correctly
  - needs to be designed correctly

## In the following:

Convert the nonlinear eigenvalue problem to a **linear** eigenvalue problem.

+ use modern linear eigenvalue solvers

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<sup>4</sup>Volker Mehrmann and Heinrich Voss. “Nonlinear eigenvalue problems: a challenge for modern eigenvalue methods”. en. In: *GAMM-Mitteilungen* 27.2 (Dec. 2004), pp. 121–152

# Equivalent polynomial eigenvalue problem

**change of variable:**

$$k_x := k_f \frac{\gamma + \gamma^{-1}}{2} \quad \Rightarrow \quad k_y = \pm k_f \frac{\gamma - \gamma^{-1}}{2i}$$

Inserting into the original **nonlinear eigenvalue problem**:

$$\underline{\underline{F}}(k_x)\underline{q} = \underline{0}, \quad \text{with} \quad \underline{\underline{F}}(k_x) = k_x^2 \underline{\underline{A}}_2 + k_x \underline{\underline{A}}_1 + \underline{\underline{A}}_0 + ik_y \underline{\underline{B}},$$

where  $k_y = \sqrt{k_f^2 - k_x^2}$ ,

results in an **equivalent**

**polynomial eigenvalue problem:**

$$\underline{\underline{P}}(\gamma)\underline{q} = \underline{0} \quad \text{with} \quad \underline{\underline{P}}(\gamma) = \underline{\underline{P}}_4 \gamma^4 + \underline{\underline{P}}_3 \gamma^3 + \underline{\underline{P}}_2 \gamma^2 + \underline{\underline{P}}_1 \gamma + \underline{\underline{P}}_0.$$

$\Rightarrow$  **complete** and **unique** problem formulation!



# Solving the leaky Lamb problem

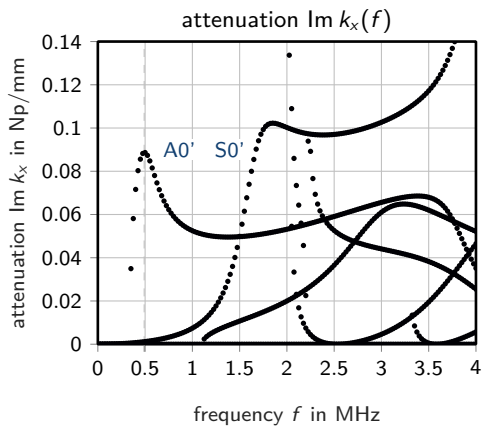
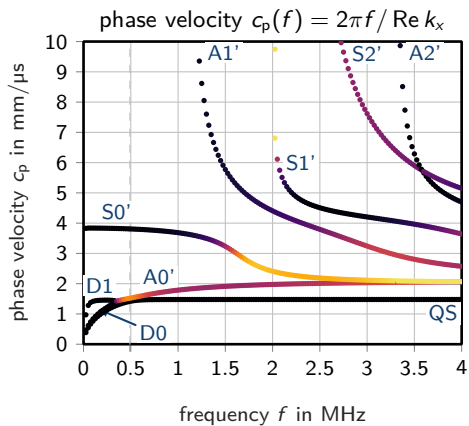
We can reliably solve the leaky Lamb wave problem by performing the following steps:

- 1 Introduce an equivalent **linear eigenvalue problem** (state space formulation)
- 2 Solve using standard methods  
 → eigenvalues  $\gamma_n$ , eigenvector  $\underline{q}_n$
- 3 Compute the wavenumbers  $k_x = k_f \frac{\gamma_n + \gamma_n^{-1}}{2}$  and corresponding  $k_y = k_f \frac{\gamma_n - \gamma_n^{-1}}{2i}$

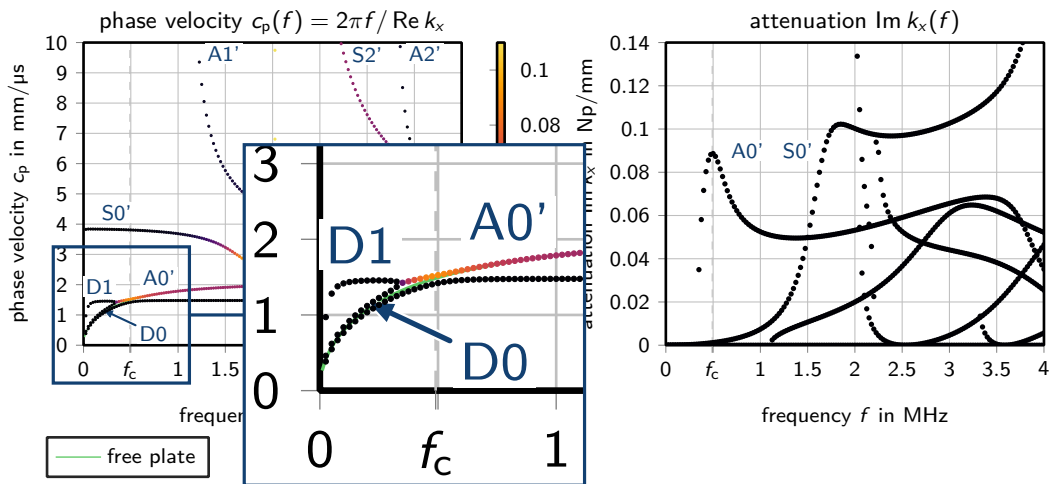
**Exploit all advantages of modern eigenvalue solvers!**

- easy to implement (here: spectral collocation)
- 150 frequency points compute in 1 s on a regular personal computer

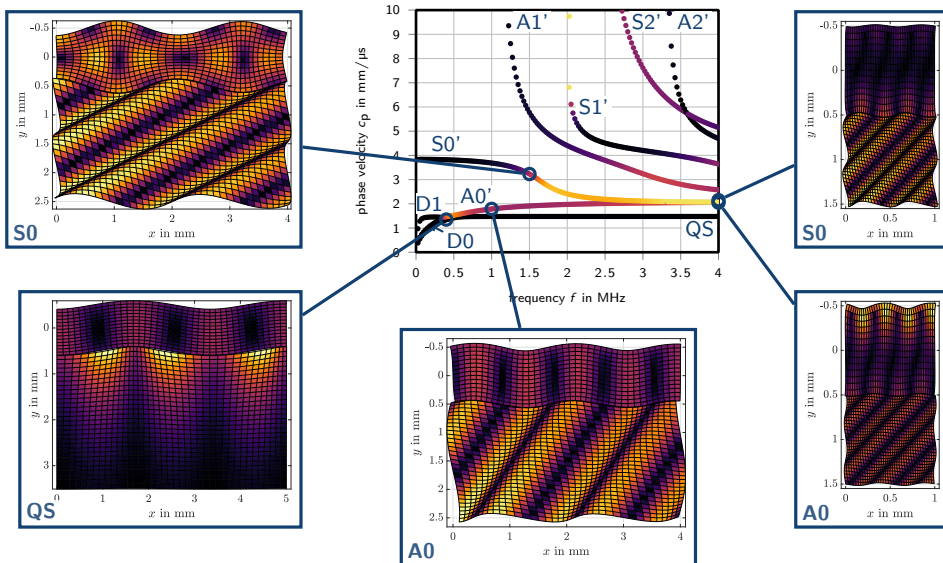
## Phase velocity and attenuation: 1 mm thick brass plate in contact on one side with water



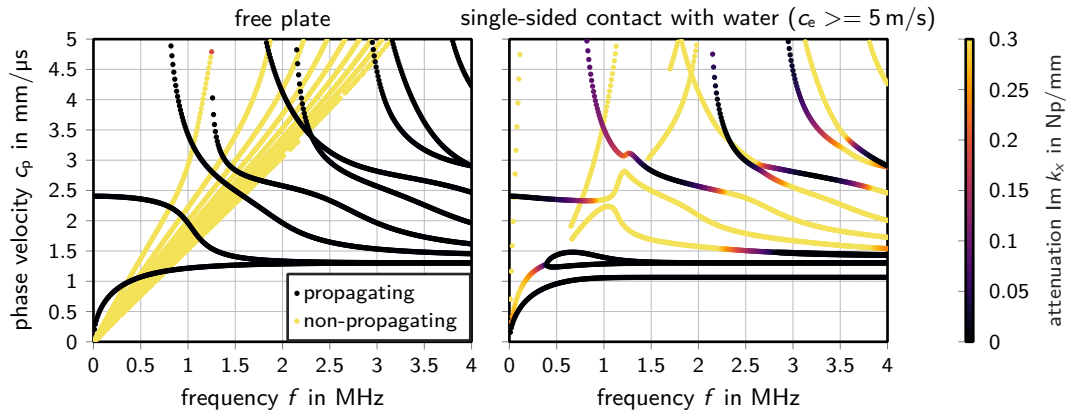
## Phase velocity and attenuation: 1 mm thick brass plate in contact on one side with water



## Displacement fields: brass plate in contact on one side with water



## Free vs. fluid loaded plate: 1 mm thick plexiglass plate



The dispersion curves of a fluid loaded plate can differ substantially from the ones of a free plate.

# Conclusions

- We calculated the dispersion characteristics of fluid loaded plates.
- They can be substantially different to the modes of a free plate.
- Avoid root-finding of the characteristic equation.
- Instead: eigenvalue problem with change of variable.

## Advantages of the proposed method:

- + linear eigenvalue problem
- + use conventional eigenvalue solvers
  - **robust**
  - **efficient**
- + leads to the **full** wavenumber spectrum

## Suitable for:

- + viscoelastic, anisotropic, inhomogeneous, and layered plates

## Restrictions:

- only plane geometries
- only non-viscous fluids
- not suitable for two different adjacent fluids